

Recap session 2

Thursday, 28 May 2020 08:12

... Duality continued

\mathbb{H}^n , .. OSL $(\mathfrak{g}_0, \theta_0)$, $\mathfrak{g} = \mathfrak{g}_0 \oplus i \cdot \mathfrak{g}_0 = \underline{k_0} \oplus \mathfrak{p}_0 \oplus i \cdot \underline{k_0} \oplus i \mathfrak{p}_0$
 $\mathfrak{g}^* = k_0 \oplus i \cdot \mathfrak{p}_0$, complex conjugation

$$\mathfrak{g}^* = \left\{ \begin{pmatrix} A & iB \\ iB^T & 0 \end{pmatrix} : A \in \mathbb{R}^{n \times n}, A^T + A = 0, B \in \mathbb{R}^{1 \times n} \right\}$$

Claim: $\mathfrak{g}^* \xrightarrow{\sim} \mathfrak{so}(n+1)$ Lie algebra isomorphism.

Proof: $\begin{pmatrix} A & iB \\ iB^T & 0 \end{pmatrix} \mapsto \begin{pmatrix} A & -B \\ B^T & 0 \end{pmatrix} = \begin{pmatrix} \text{Id}_n & \\ & -i \end{pmatrix} \begin{pmatrix} A & iB \\ iB^T & 0 \end{pmatrix} \begin{pmatrix} \text{Id}_n & \\ & i \end{pmatrix}$ \square

$\mathfrak{g}^* \xrightarrow{\text{complex conjugation}} \mathfrak{g}^*$ We get dual OSL which is isomorphic to $(\mathfrak{so}(n+1), \theta^*)$, and $k^* \cong \mathfrak{so}(n)$

$\mathfrak{so}(n+1) \xrightarrow{\theta^*} \mathfrak{so}(n+1)$

~~\mathbb{H}^n~~ $(\mathbb{H}^n)^* = \mathfrak{so}(n+1) / \mathfrak{so}(n) = \mathbb{S}^n$ $\mathfrak{so}(n+1)$ connected semisimple

Actually: $G := \text{Aut}(\mathfrak{g}^*)^0 = \text{Aut}(\mathfrak{so}(n+1))^0 \cong \text{Ad}(\mathfrak{so}(n+1))_{\mathfrak{so}(n+1)}$

What is K ? ... $K \cong \mathfrak{so}(n)$

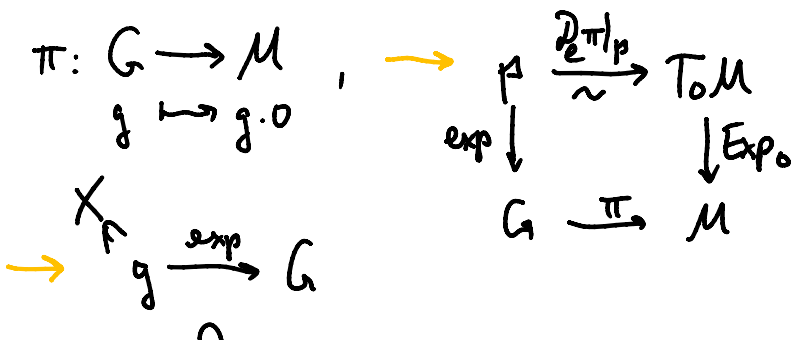
$\mathfrak{so}(n+1) \xrightarrow{\cong} \mathfrak{so}(n+1) / \mathbb{Z}(\mathfrak{so}(n+1)) = \begin{cases} \cong \mathfrak{so}(n+1) & \text{if } n \text{ is even} \\ \cong \mathfrak{so}(n+1) / \pm \text{Id} & \text{if } n \text{ is odd} \end{cases}$

$\mathfrak{so}(n+1)$ connected.

$\Rightarrow M^* = G/K = \dots, \mathbb{S}^n \text{ or } \mathbb{R}P^n$

Note: If M is of non-compact type, then $(M^*)^* = M$
 of compact type: $((\mathbb{R}P^2)^*)^* = (\mathbb{H}^2)^* = \mathbb{S}^2$

Riemannian Geometry



To prove this we need transvections.

$T_t := S_{\delta(\xi)} \circ S_{\gamma(0)}$

$D\Sigma_{\delta(s)_t} : T_{\gamma(s)} M \rightarrow T_{\gamma(s+t)} M$

→ $g \xrightarrow{\exp} G$

$$\begin{array}{ccc} T_x g & \xrightarrow{d_x \exp} & T_{\exp(x)} G \\ \downarrow & & \uparrow d_x L_{\exp(x)} \\ g & \xrightarrow{\quad} & g = T_{\text{Id}} G \\ Y & \mapsto & \sum_{n=0}^{\infty} \frac{(-\text{ad}(Y))^n}{(n+1)!} \end{array}$$

$D\tau_{\frac{d}{dt}} : T_{r(s)} M \rightarrow T_{r(s+t)} M$
implements the parallel transport.

→ $\forall X, Y, Z \in \mathfrak{p} \Rightarrow \bar{X}, \bar{Y}, \bar{Z} \in T_0 M$
 $\Rightarrow R(\bar{X}, \bar{Y})\bar{Z} = -\overline{[X, Y], Z}$

Sectional curvature:

$$\sigma_p(Rv \oplus Rw) := g_p(R(v, w)v, w)$$

→ If M is compact type, then $\sigma_p \geq 0$

M is non-compact type, then $\sigma_p \leq 0$

Euclidean type, then $\sigma_p = 0$.

→ If M is of compact type, then: M is compact
 $Is(M)^0$ is compact..

→ If M is of non-compact type, then:

- $\text{Exp}_0 : T_0 M \rightarrow M$ is a diffeomorphism.
 $\Rightarrow M$ is simply connected.

- $\rho \times K \rightarrow G$ is a diffeomorphism.
 $(X, k) \mapsto \exp(X) \cdot k$

- M is CAT(0) space.

Lie triple systems.

Definition 2.44. Let \mathfrak{g} be a Lie algebra. A subset $\mathfrak{n} \subseteq \mathfrak{g}$ is a Lie triple system if $\mathfrak{n}, [\mathfrak{n}, \mathfrak{n}] \subseteq \mathfrak{n}$.

Lie triple systems correspond to totally geodesic subspaces.

Special case: If \mathfrak{n} Euclidean, $[\mathfrak{n}, \mathfrak{n}] = 0$, $\text{Exp}_0(d_e \pi(\mathfrak{n}))$ is a flat.

Ex: $SL(n, \mathbb{R}) / SO(n)$, $\mathfrak{g} = SL(n, \mathbb{R})$, $\Theta(X) = -X^T$,

$n=2$: $SL(2, \mathbb{R}) = \mathfrak{k} \oplus \mathfrak{p} = \mathfrak{so}(2) \oplus \{X : X^T = X\}$

$n=2$: $SL(2, \mathbb{R}) = \mathfrak{k} \oplus \mathfrak{p} = \mathfrak{so}(2) \oplus \{X : X^T = -X\}$
 $= \langle \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \rangle \oplus \langle \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \rangle$

$\mathfrak{a} := \langle \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \rangle$ Euclidean, abelian subspace of \mathfrak{p} .

Let $H = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$, let \mathfrak{a}' be another abelian subspace $\mathfrak{a} \subset \mathfrak{a}' \subset \mathfrak{p}$

$\mathfrak{a}' \subset \mathcal{Z}_{\mathfrak{g}}(H) \cap \mathfrak{p} = \{X \in \mathfrak{p} : [X, H] = 0\} = \langle \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \rangle = \mathfrak{a}$.

$\Rightarrow \mathfrak{a}$ is maximal abelian subspace.

$$\left[\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \right] = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} - \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & -2 \\ 2 & 0 \end{pmatrix} \neq 0$$

Def: Rank of \mathfrak{g}/M is the dimension of the maximal abelian subspace / flat.

$\Rightarrow n=2$: $SL(2, \mathbb{R})/SO(2)$ has rank 1.

For $SL(n, \mathbb{R})/SO(n)$ we consider $\mathfrak{a} = \langle \begin{pmatrix} 1 & & & \\ & -1 & & \\ & & \ddots & \\ & & & -1 \end{pmatrix}, \begin{pmatrix} 0 & 1 & & \\ & -1 & & \\ & & \ddots & \\ & & & 0 \end{pmatrix}, \dots, \begin{pmatrix} & & & 0 \\ & & & 1 \\ & & & \ddots \\ & & & & -1 \end{pmatrix} \rangle$

$H = \begin{pmatrix} -\frac{n}{2} & & & \\ & \ddots & & \\ & & \frac{n}{2} & \end{pmatrix}$, $\mathcal{Z}_{\mathfrak{g}}(H) \cap \mathfrak{p} = \mathfrak{a} \Rightarrow \mathfrak{a}$ is maximal.

$\Rightarrow \text{rank} \left(\frac{SL(n, \mathbb{R})}{SO(n)} \right) = n-1$

of non-compact type.

$M = M_0 \times \underline{M_-} \times M_+$

$\text{rank}(M_0) = \dim(M_0) = n$, $M_0 = \mathbb{R}^n$

Remark: $\text{rank}(\mathbb{H}^n) = 1$, $\text{rank} \left(\frac{SL(n, \mathbb{R})}{SO(n)} \right) \neq 1$ for $n \geq 3$.

$\frac{O(n, 1)}{SO(n)} = \mathbb{H}^n \neq \frac{SL(n, \mathbb{R})}{SO(n)} = \mathbb{P}_1(n)$

Root spaces

Ex: $SL(2, \mathbb{R})$, $\mathfrak{a} = \langle \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \rangle$ maximal flat.

$\text{ad}(H): \mathfrak{g} \rightarrow \mathfrak{g}$, $\text{ad}(H) \begin{pmatrix} a & b \\ c & -a \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} a & b \\ c & -a \end{pmatrix} - \begin{pmatrix} a & b \\ c & -a \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$
 $X \mapsto [H, X] = \begin{pmatrix} a & b \\ c & a \end{pmatrix} - \begin{pmatrix} a & -b \\ c & a \end{pmatrix} = \begin{pmatrix} 0 & 2b \\ -2c & 0 \end{pmatrix}$

$\mathfrak{g} = \langle \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \rangle = \mathfrak{a} = \{X \in \mathfrak{g} : \text{ad}(H)X = 2 \cdot X\}$

$$E_2(\text{ad}(H)) = \langle \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \rangle = \mathfrak{g}_2 = \{ X \in \mathfrak{g} : \text{ad}(H)X = 2 \cdot X \}$$

$$E_{-2}(\text{ad}(H)) = \langle \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \rangle \Rightarrow \mathfrak{g} = \mathfrak{g}_0 \oplus \mathfrak{g}_2 \oplus \mathfrak{g}_{-2} = \mathfrak{a} \oplus \langle \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \rangle$$

$$E_0(\text{ad}(H)) = \mathfrak{a} \quad \text{Roots: are } 2, -2,$$

$$n=3: \mathfrak{g} = \mathfrak{sl}(3, \mathbb{R}) : \mathfrak{a} = \langle \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \rangle =: \langle H_1, H_2 \rangle$$

$$\text{ad}(H_1) \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix} = \begin{pmatrix} 1 & & \\ & -1 & \\ & & 0 \end{pmatrix} \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix} - \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix} \begin{pmatrix} 1 & & \\ & -1 & \\ & & 0 \end{pmatrix}$$

$$= \begin{pmatrix} a & b & c \\ -d & -e & -f \\ 0 & 0 & 0 \end{pmatrix} - \begin{pmatrix} a & -b & 0 \\ d & -e & 0 \\ g & -h & 0 \end{pmatrix} = \begin{pmatrix} 0 & 2b & c \\ -2d & 0 & -f \\ -g & h & 0 \end{pmatrix}$$

$$a+d+i=0$$

\mathfrak{g}_λ	$\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$	\mathfrak{a}
$\text{ad}(H_1)$	2	1	-2	-1	-1	1	0
$\text{ad}(H_2)$	-1	1	1	2	-1	-2	0

Roots: α $\alpha+\beta$ $-\alpha$ β $-\alpha-\beta$ $-\beta$ 0 ← not a root.

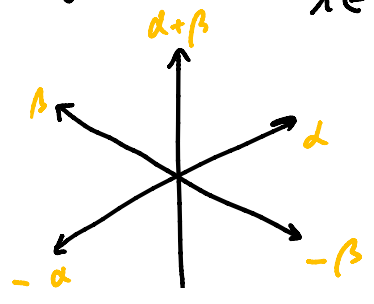
Root: $\alpha \in \mathfrak{a}^* : \alpha : \mathfrak{a} \rightarrow \mathbb{R}, \beta : \mathfrak{a} \rightarrow \mathbb{R}$
 $H_1 \mapsto 2, H_2 \mapsto -1$ $H_1 \mapsto -1, H_2 \mapsto 2$

$$\mathfrak{g}_\alpha = \{ X \in \mathfrak{sl}(n, \mathbb{R}) : \forall H \in \mathfrak{a} : [H, X] = \alpha(H) \cdot X \}$$

$[H_1, X] = 2 \cdot X$

The set of roots = $\Sigma = \{ \alpha, \beta, \alpha+\beta, -\alpha, -\beta, -\alpha-\beta \}$

$$\mathfrak{g} = \mathfrak{g}_0 \oplus \sum_{\lambda \in \Sigma} \mathfrak{g}_\lambda = \mathfrak{a} \oplus \langle \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \dots, \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \rangle$$





Classification

Irreducible simply connected RST of compact type :

A) K is a compact simple Lie group. $K \times K / \Delta \cong K$ RST.

B) $(SL(n, \mathbb{R}) / SO(n))^*$

Label	G	K	Dimension	Rank	Geometric interpretation
AI	SU(n)	SO(n)	$(n-1)(n+2)/2$	$n-1$	Space of real structures on \mathbb{C}^n which leave the complex determinant invariant
AII	SU(2n)	Sp(n)	$(n-1)(2n+1)$	$n-1$	Space of quaternionic structures on \mathbb{C}^{2n} compatible with the Hermitian metric
AIII	SU(p+q)	S(U(p) × U(q))	2pq	min(p,q)	Grassmannian of complex p-dimensional subspaces of \mathbb{C}^{p+q}
BDI	SO(p+q)	SO(p) × SO(q)	pq	min(p,q)	Grassmannian of oriented real p-dimensional subspaces of \mathbb{R}^{p+q}
DIII	SO(2n)	U(n)	$n(n-1)$	[n/2]	Space of orthogonal complex structures on \mathbb{R}^{2n}
CI	Sp(n)	U(n)	$n(n+1)$	n	Space of complex structures on \mathbb{H}^n compatible with the inner product
CII	Sp(p+q)	Sp(p) × Sp(q)	4pq	min(p,q)	Grassmannian of quaternionic p-dimensional subspaces of \mathbb{H}^{p+q}
EI	E_6	Sp(4)/{±I}	42	6	
EII	E_6	SU(6) · SU(2)	40	4	Space of symmetric subspaces of $(\mathbb{C} \otimes \mathbb{O})P^2$ isometric to $(\mathbb{C} \otimes \mathbb{H})P^2$
EIII	E_6	SO(10) · SO(2)	32	2	Complexified Cayley projective plane $(\mathbb{C} \otimes \mathbb{O})P^2$
EIV	E_6	F_4	26	2	Space of symmetric subspaces of $(\mathbb{C} \otimes \mathbb{O})P^2$ isometric to $\mathbb{O}P^2$
EVI	E_7	SU(8)/{±I}	70	7	
EVII	E_7	SO(12) · SU(2)	64	4	Rosenfeld projective plane $(\mathbb{H} \otimes \mathbb{O})P^2$ over $\mathbb{H} \otimes \mathbb{O}$
EVIII	E_7	$E_6 \cdot SO(2)$	54	3	Space of symmetric subspaces of $(\mathbb{H} \otimes \mathbb{O})P^2$ isomorphic to $(\mathbb{C} \otimes \mathbb{O})P^2$
EIX	E_8	Spin(16)/{±vol}	128	8	Rosenfeld projective plane $(\mathbb{O} \otimes \mathbb{O})P^2$
EIX	E_8	$E_7 \cdot SU(2)$	112	4	Space of symmetric subspaces of $(\mathbb{O} \otimes \mathbb{O})P^2$ isomorphic to $(\mathbb{H} \otimes \mathbb{O})P^2$
FI	F_4	Sp(3) · SU(2)	28	4	Space of symmetric subspaces of $\mathbb{O}P^2$ isomorphic to $\mathbb{H}P^2$
FII	F_4	Spin(9)	16	1	Cayley projective plane $\mathbb{O}P^2$
G	G_2	SO(4)	8	2	Space of subalgebras of the octonion algebra \mathbb{O} which are isomorphic to the quaternion algebra \mathbb{H}